

CONVEYOR ROLLERS

EXCELLENT QUALITY AND RELIABILITY



RANGE OF APPLICATION



Packaging and logistics

Used in warehouses requiring high-speed cargo handling and maximum efficiency with minimal floor space occupancy.



Distribution centers and warehousing

When high performance, accuracy, reliability, as well as high process dynamics are required



Distribution of Pharmaceutical Products

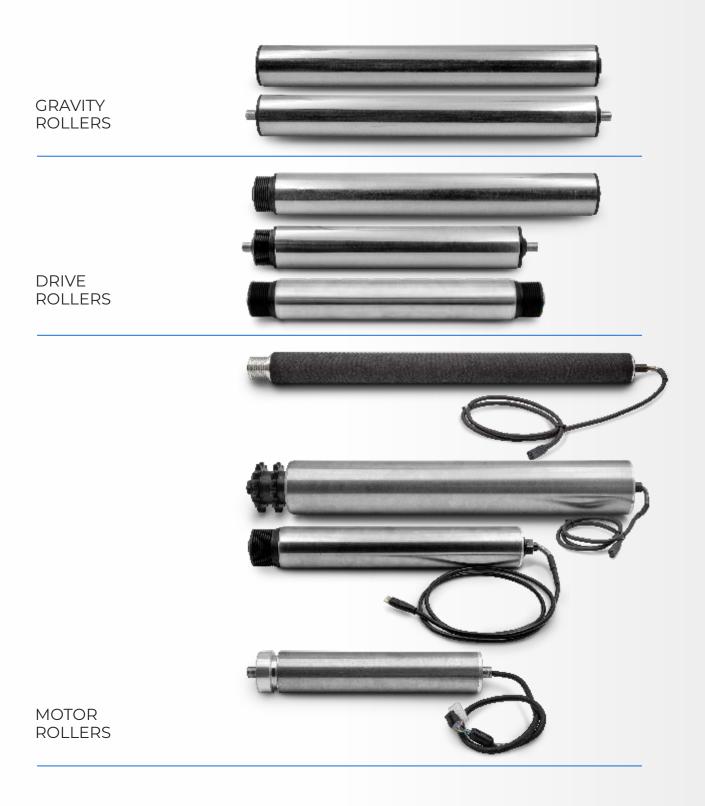
Allow automatic order picking, packaging, and screening for picking errors.



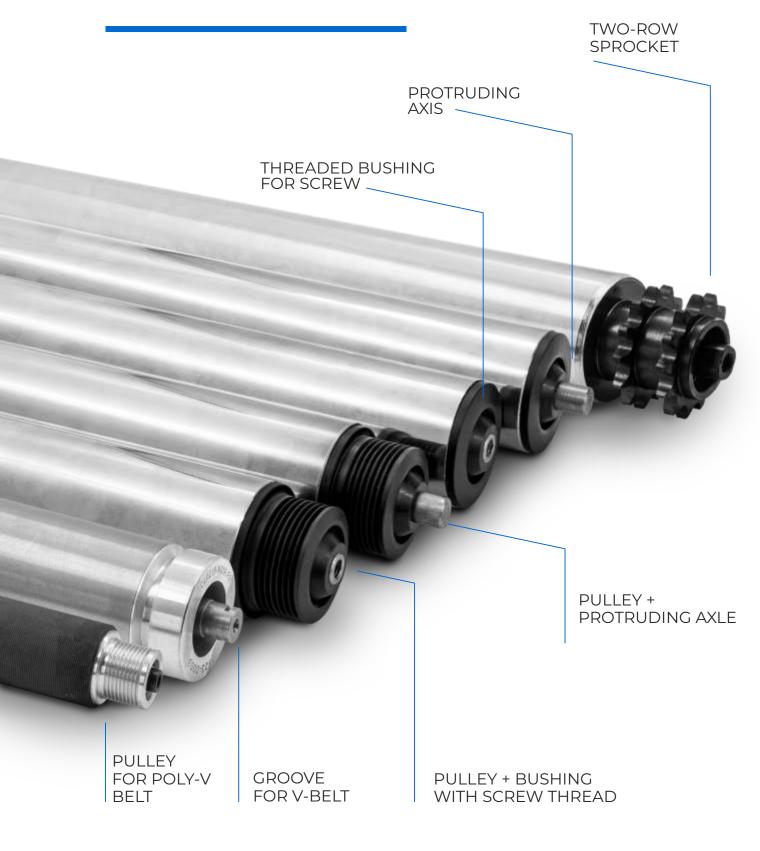
Mail, parcels, and e-commerce

Allow for rapid sorting where it is critically important.

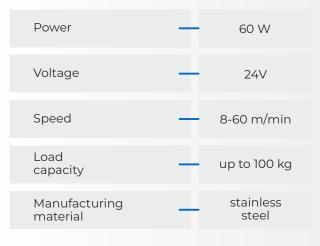
ROLLER TYPES:



END TYPES AND MOUNTING DESIGN:

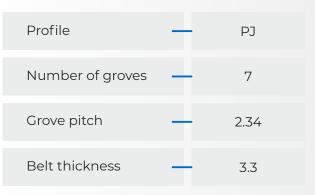


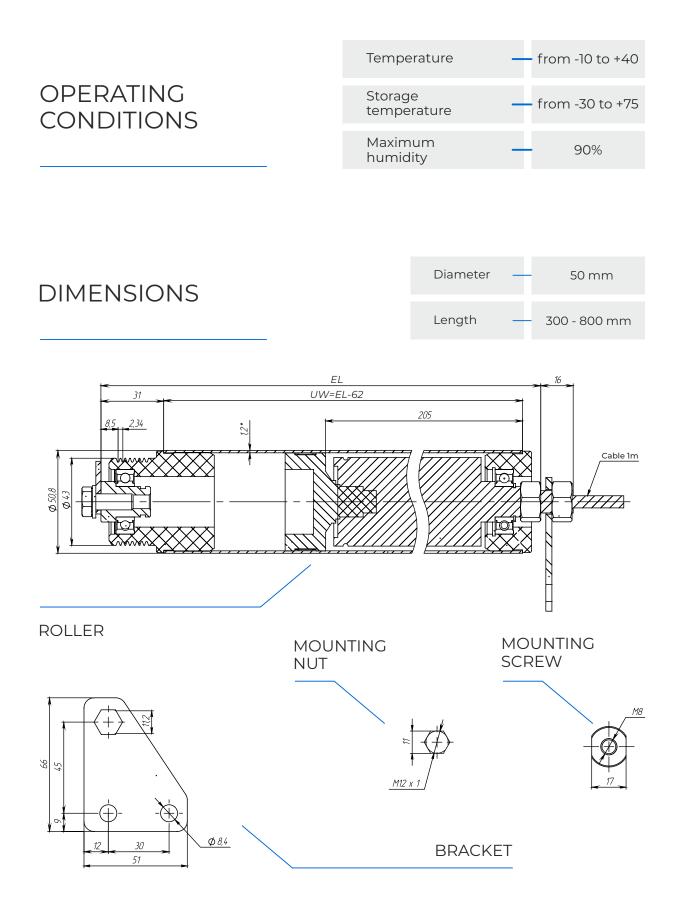




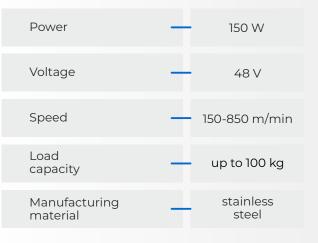


PULLEY FOR POLY-V BELT

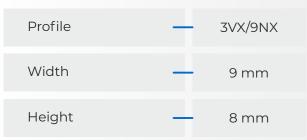


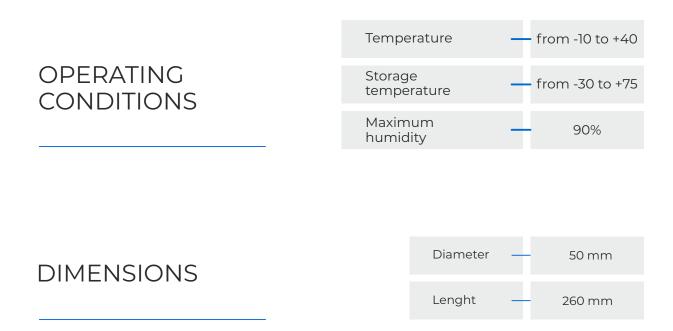


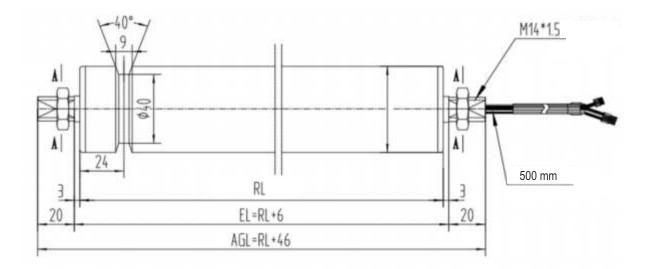
TECHNICAL SPECIFICATIONS

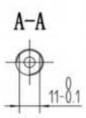


GROOVE FOR V-BELT





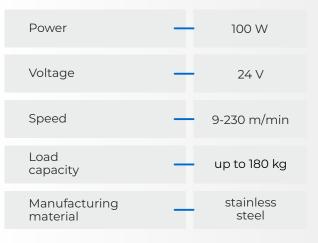




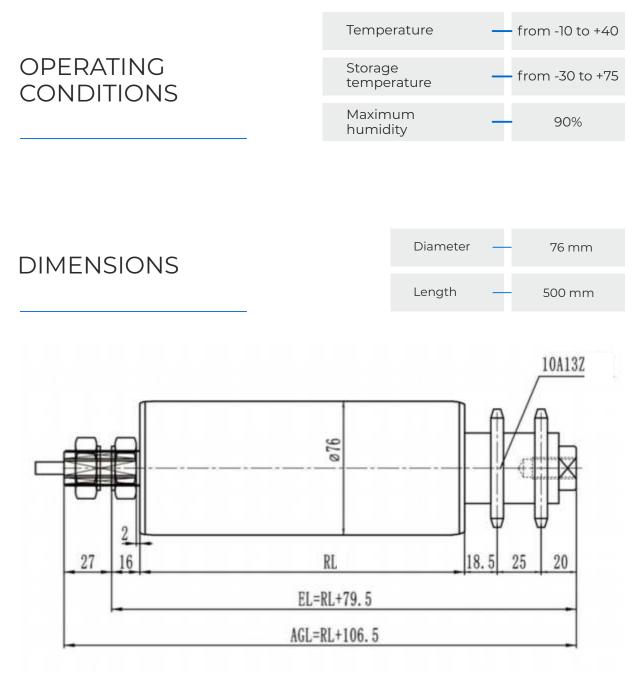
TECHNICAL SPECIFICATIONS



TWO-ROW SPROCKET (08B14T)

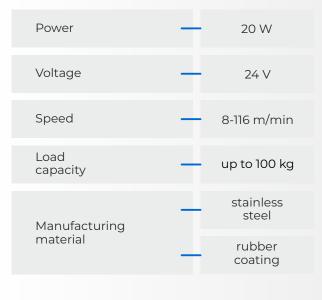








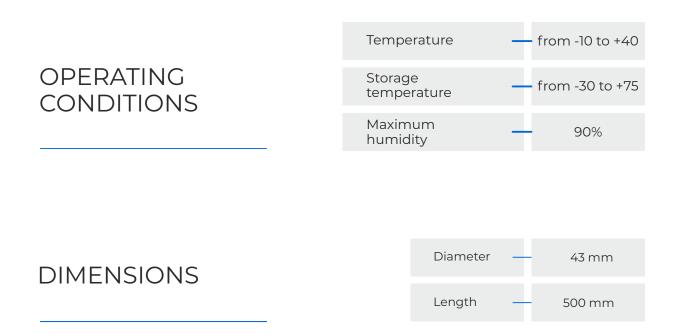
TECHNICAL SPECIFICATIONS

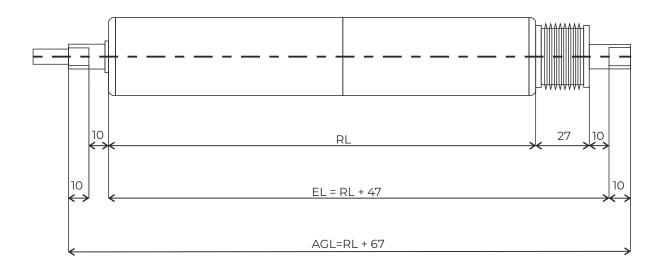




ProfilePJNumber of groves9Grove pitch2,34Belt thickness21,06

PULLEY FOR POLY-V BELT



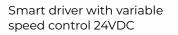






CONTROLLER

BCD-B-24-120A





CE

MAIN FUNCTIONS:



3 LED states

LED indication of error/alarm output signal



EBS/Servo brake support

Repeated recovery of working signal

Support for RS-485 communication via Modbus RTU protocol



Overheating and overcurrent protection of the drive board and motor roller

Internal 10 A fuse chip

Protection against incorrect power supply polarity

High voltage and low voltage protection



Selectable default rotation direction

The motor roller supports forward and reverse rotation



Removable power and signal terminals

External switching between NPN and PNP modes

Connection to external voltage 0-10 V for variable speed control



PID control and rotation speed control mode, 32 speed options

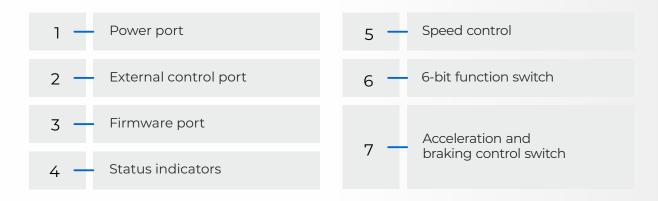
16 acceleration/deceleration settings

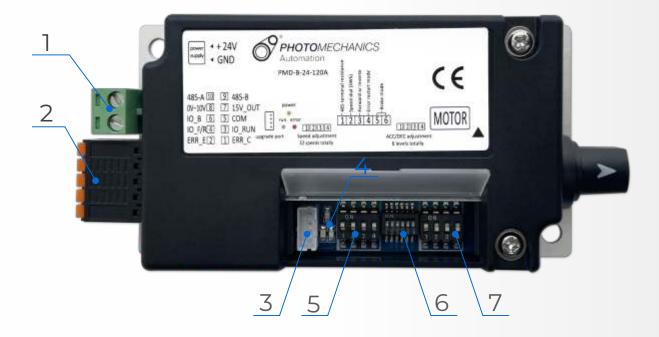
Variable speed control

Multi-segment speed can be configured

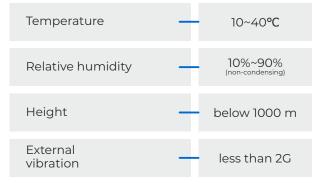
Open/closed loop operation speed

CONTROL

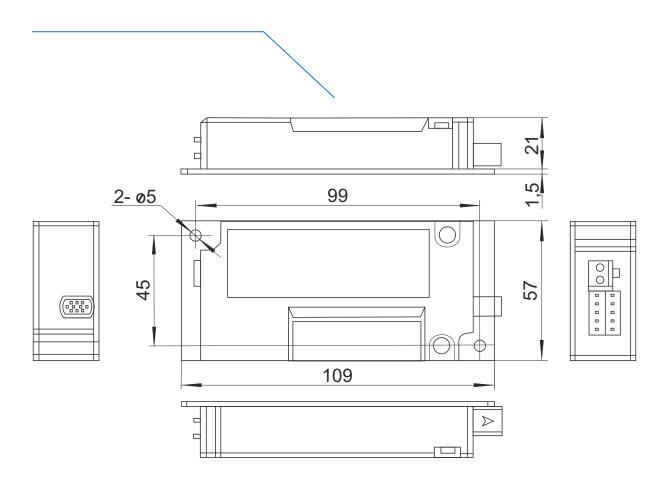




OPERATION ENVIRONMENT



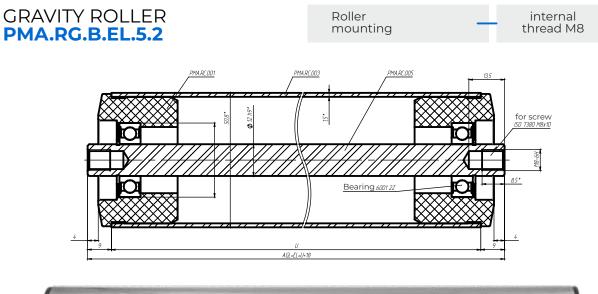
DIMENSIONS



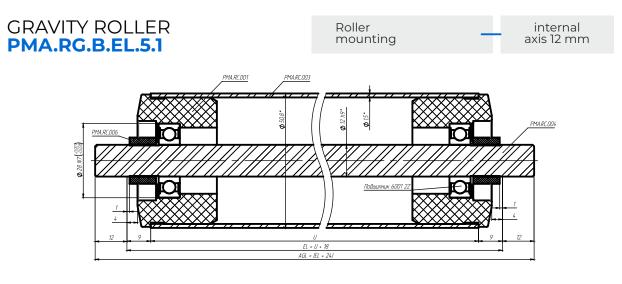


DRIVE AND GRAVITY ROLLERS



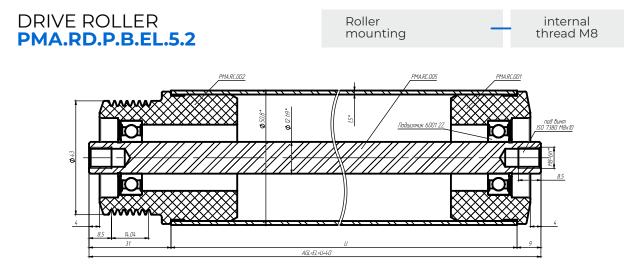




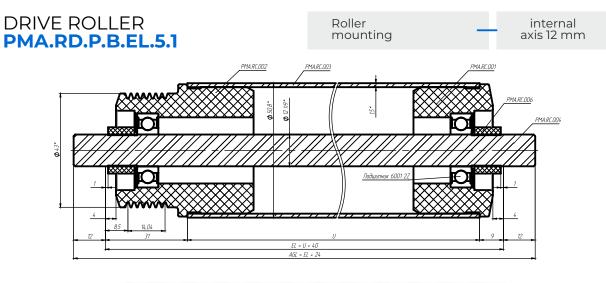




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